

ERRATUM TO THE ARTICLE HAMILTON–JACOBI EQUATIONS FOR OPTIMAL CONTROL ON JUNCTIONS AND NETWORKS

YVES ACHDOU¹, SALOMÉ OUDET² AND NICOLETTA TCHOU²

Abstract. We correct a mistake which affects an intermediate result, namely the second part of Lemma 4.5. The main results of the article are unchanged.

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The second part of Lemma 4.5, concerning subsolutions, is not correct in the published version of the paper. Recall that we are interested in proving a comparison principle for sub and super solutions of

$$\lambda u(x) + \sup_{(\zeta, \xi) \in \text{FL}(x)} \{-Du(x, \zeta) - \xi\} = 0 \quad \text{in } \mathcal{G}. \quad (3.1)$$

Lemma 4.5 must be modified as follows:

Lemma 4.5. *Let $v : \mathcal{G} \rightarrow \mathbb{R}$ be a viscosity supersolution of (3.1) in \mathcal{G} . Then if $x \in J_i \setminus \{0\}$, we have for all $t > 0$,*

$$v(x) \geq \inf_{\alpha_i(\cdot), \theta_i} \left(\int_0^{t \wedge \theta_i} \ell_i(y_x^i(s), \alpha_i(s)) e^{-\lambda s} ds + v(y_x^i(t \wedge \theta_i)) e^{-\lambda(t \wedge \theta_i)} \right), \quad (4.8)$$

where $\alpha_i \in L^\infty(0, \infty; A_i)$, y_x^i is the solution of $y_x^i(t) = x + \left(\int_0^t f_i(y_x^i(s), \alpha_i(s)) ds \right) e_i$ and θ_i is such that $y_x^i(\theta_i) = 0$ and θ_i lies in $[\tau_i, \bar{\tau}_i]$, where τ_i is the exit time of y_x^i from $J_i \setminus \{0\}$ and $\bar{\tau}_i$ is the exit time of y_x^i from J_i .

Remark. Concerning subsolutions, the comparison results of Barles–Perthame [2] imply the following sub-optimality principle for subsolutions that will not be needed in the sequel: let w be a continuous viscosity

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¹ Université Paris Diderot, Sorbonne Paris Cité, Laboratoire Jacques-Louis Lions, UMR 7598, UPMC, CNRS, 75205 Paris, France. achdou@ljl11.univ-paris-diderot.fr

² IRMAR, Université de Rennes 1, Rennes, France. nicoletta.tchou@univ-rennes1.fr

subsolution of (3.1) in \mathcal{G} . If $x \in J_i \setminus \{0\}$, we have for all $t > 0$,

$$w(x) \leq \inf_{\alpha_i(\cdot)} \sup_{\theta_i} \left(\int_0^{t \wedge \theta_i} \ell_i(y_x^i(s), \alpha_i(s)) e^{-\lambda s} ds + w(y_x^i(t \wedge \theta_i)) e^{-\lambda(t \wedge \theta_i)} \right), \tag{4.9}$$

where $\alpha_i \in L^\infty(0, \infty; A_i)$, y_x^i is the solution of $y_x^i(t) = x + \left(\int_0^t f_i(y_x^i(s), \alpha_i(s)) ds \right) e_i$ and θ_i is such that $y_x^i(\theta_i) = 0$ and θ_i lies in $[\tau_i, \bar{\tau}_i]$, where τ_i is the exit time of y_x^i from $J_i \setminus \{O\}$ and $\bar{\tau}_i$ is the exit time of y_x^i from J_i .

Then, Theorem 4.6 should be very slightly modified as follows (the very minor changes in the proof do not need to be written):

Theorem 4.6. *Assume [H0], [H1], [H2] and [H3]. Let $r > 0$ be given by Lemma 4.2: any bounded subsolution of (3.1) is Lipschitz continuous in $B(O, r) \cap \mathcal{G}$. Let $v : \mathcal{G} \rightarrow \mathbb{R}$ be a viscosity supersolution of (3.1), bounded from below by $-c|x| - C$ for two positive numbers c and C . Either [A] or [B] below is true:*

[A] *There exists a sequence $(\eta_k)_{k \in \mathbb{N}}$ of positive real numbers such that $\lim_{k \rightarrow +\infty} \eta_k = \eta > 0$, an index $i \in \{1, \dots, N\}$ and a sequence $x_k \in J_i$ such that $x_k \in J_i \setminus \{O\}$ and $\lim_{k \rightarrow +\infty} x_k = O$ satisfying the following: for any $k \in \mathbb{N}$, there exists a control law α_i^k such that the corresponding trajectory y_{x_k} remains in $J_i \cap B(O, r)$ in the time interval $[0, \eta_k]$, i.e. $y_{x_k}(s) \in J_i \cap B(O, r)$ for all $s \in [0, \eta_k]$, and is such that*

$$v(x_k) \geq \int_0^{\eta_k} \ell_i(y_{x_k}(s), \alpha_i^k(s)) e^{-\lambda s} ds + v(y_{x_k}(\eta_k)) e^{-\lambda \eta_k} \tag{4.10}$$

[B]

$$\lambda v(O) + H_O^T \geq 0. \tag{4.11}$$

A new lemma is needed to replace the second part of Lemma 4.5:

Lemma 4.7. *Assume [H0], [H1], [H2] and [H3]. Let $r > 0$ be given by Lemma 4.2: any bounded subsolution of (3.1) is Lipschitz continuous in $B(O, r) \cap \mathcal{G}$. Consider $i \in \{1, \dots, N\}$, $x \in (J_i \setminus \{O\}) \cap B(O, r)$, $\alpha_i \in L^\infty(0, \infty; A_i)$. Let $\eta > 0$ be such that $y_x(t) = x + \left(\int_0^t f_i(y_x(s), \alpha_i(s)) ds \right) e_i$ belongs to $J_i \cap B(O, r)$ for any $t \in [0, \eta]$. For any bounded viscosity subsolution v of (3.1),*

$$v(x) \leq \int_0^\eta \ell_i(y_x(t), \alpha_i(t)) e^{-\lambda t} dt + v(y_x(\eta)) e^{-\lambda \eta}. \tag{a}$$

Proof. Since v is Lipschitz continuous in $B(O, r) \cap J_i$, the function $t \mapsto v(y_x(t)) e^{-\lambda t}$ is Lipschitz continuous in $[0, \eta]$. Let us define the sets $K_O = \{t \in (0, \eta) : y_x(t) = O\}$ and $K_O^c = [0, \eta] \setminus K_O$. It is clear that K_O is closed and that K_O^c is an open subset of $[0, \eta]$. We first observe that, from Stampacchia's theorem,

$$\int_0^\eta 1_{K_O}(t) \frac{d}{dt} (v(y_x(t)) e^{-\lambda t}) dt = -\lambda v(O) \int_0^\eta 1_{K_O}(t) e^{-\lambda t} dt.$$

Therefore, we deduce from Lemma 4.3 that

$$\int_0^\eta 1_{K_O}(t) \frac{d}{dt} (v(y_x(t)) e^{-\lambda t}) dt \geq H_O^T \int_0^\eta 1_{K_O}(t) dt \geq - \int_0^\eta \ell_i(O, \alpha_i(t)) 1_{K_O}(t) dt = - \int_0^\eta \ell_i(y_x(t), \alpha_i(t)) 1_{K_O}(t) dt. \tag{b}$$

On the other hand, since K_O^c is an open subset of $[0, \eta]$, there exists a countable family of disjoint intervals $(\omega_j)_{j \in J}$, $\omega_j \subset [0, \eta]$ such that $K_O^c = \bigcup_{j \in J} \omega_j$. Let $a_j < b_j$ be the lower and upper endpoints of ω_j . We can assume that $[a_j, b_j] \cap [a_k, b_k] = \emptyset$ if $j \neq k$.

From a classical suboptimality principle, see ([1], Thm. III.2.33), we see that for any $j \in J$,

$$v(y_x(b_j))e^{-\lambda b_j} - v(y_x(a_j))e^{-\lambda a_j} \geq - \int_{a_j}^{b_j} \ell_i(y_x(t), \alpha_i(t))e^{-\lambda t} dt.$$

Noting that

$$v(y_x(b_j))e^{-\lambda b_j} - v(y_x(a_j))e^{-\lambda a_j} = \int_0^\eta \frac{d}{dt} (v(y_x(t))e^{-\lambda t}) 1_{(a_j, b_j)}(t) dt,$$

and summing over $j \in J$, we obtain that

$$\int_0^\eta 1_{K_\mathcal{G}}(t) \frac{d}{dt} (v(y_x(t))e^{-\lambda t}) dt \geq - \int_0^\eta \ell_i(y_x(t), \alpha_i(t)) 1_{K_\mathcal{G}}(t) dt. \tag{c}$$

We get (a) by summing (b) and (c). □

The main comparison result holds but its proof is modified.

Theorem 5.1. *Assume [H0], [H1], [H2] and [H3]. Let $u : \mathcal{G} \rightarrow \mathbb{R}$ be a bounded viscosity subsolution of (3.1), and $v : \mathcal{G} \rightarrow \mathbb{R}$ be a bounded viscosity supersolution of (3.1). Then $u \leq v$ in \mathcal{G} .*

Proof. It is a simple matter to check that there exists a positive real number M such that the function $\psi(x) = -|x|^2 - M$ is a viscosity subsolution of (3.1). For $0 < \mu < 1$, μ close to 1, the function $u_\mu = \mu u + (1 - \mu)\psi$ is a viscosity subsolution of (3.1), which tends to $-\infty$ as $|x|$ tends to $+\infty$. Let M_μ be the maximal value of $u_\mu - v$ which is reached at some point \bar{x}_μ .

We want to prove that $M_\mu \leq 0$.

- (1) If $\bar{x}_\mu \neq O$, then we introduce the function $u_\mu(x) - v(x) - d^2(x, \bar{x}_\mu)$, which has a strict maximum at \bar{x}_μ , and we double the variables, i.e. for $0 < \varepsilon \ll 1$, we consider

$$u_\mu(x) - v(y) - d^2(x, \bar{x}_\mu) - \frac{d^2(x, y)}{\varepsilon^2}.$$

Classical arguments then lead to the conclusion that $u_\mu(\bar{x}_\mu) - v(\bar{x}_\mu) \leq 0$, thus $M_\mu \leq 0$.

- (2) If $\bar{x}_\mu = O$. We use Theorem 4.6; we have two possible cases:

[B] $\lambda v(O) \geq -H_O^T$.

From Lemma 4.3, $\lambda u(O) + H_O^T \leq 0$. Therefore, we obtain that $u_\mu(O) \leq v(O)$, thus $M_\mu \leq 0$.

[A] With the notations of Theorem 4.6,

$$v(x_k) \geq \int_0^{\eta_k} \ell_i(y_{x_k}(s), \alpha_i^k(s))e^{-\lambda s} ds + v(y_{x_k}(\eta_k))e^{-\lambda \eta_k}.$$

Moreover, since $y_{x_k}(s) \in J_i \cap B(O, r)$ for all $s \in [0, \eta_k]$, Lemma 4.7 can be applied and yields that

$$u_\mu(x_k) \leq \int_0^{\eta_k} \ell_i(y_{x_k}(s), \alpha_i^k(s))e^{-\lambda s} ds + u_\mu(y_{x_k}(\eta_k))e^{-\lambda \eta_k}.$$

Therefore

$$u_\mu(x_k) - v(x_k) \leq (u_\mu(y_{x_k}(\eta_k)) - v(y_{x_k}(\eta_k)))e^{-\lambda \eta_k}.$$

Letting k tend to $+\infty$, we find that $M_\mu \leq M_\mu e^{-\lambda \eta}$, which implies that $M_\mu \leq 0$

We conclude by letting μ tend to 1. □

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